

## Plan

(1) IntroductionExamples to start withInduction Trees
(4) Initiation to the practice of decision trees with partyQuality of the treeDiscriminating with typical sequencing pattern

```
Mobility Tree
Introduction
Organizin
```

Organizing knowledge in tree form

- Giving a hierarchical presentation of knowledge of a domain in tree form facilitates understanding.
- An Aristotelean tree, splits concepts according to simple yes-no questions (analytical tree)
- Example: What kind of longitudinal data do you have?


```
Mobility Tree
    Introduction
        Trees induced from data
```


## Trees induced from data

- The previous tree is a logical analysis of possible situations.
- Here, we are interested in tree structure induced from data
- Empirical trees derived from data.
- Aim is to partition data into groups:
- that are as homogeneous as possible (minimal within class diversity)
- that differ as much as possible from each other (maximal between class diversity)


## Supervised and unsupervised trees

- Supervised tree: There is a (univariate or multivariate) target variable and branching is defined in terms of the values of covariates.
- Diversity is measured in the space of this target variable.
- Examples: Classification tree, regression tree, survival tree, ...
- Unsupervised tree: There is no specific target variable and no branching condition in terms of values of variables.
- Diversity is measured in the space of all considered variables.
- Example: Dendrogram representing hierarchical clustering.


## obility Tree

Examples to start with
Social mobility over 3 generations

## Social mobility over 3 generations

- Using data from acts of marriage of 19th century Geneva Ryczkowska (2003)
- On each act:
- profession of the groom
- profession of the father (at son's marriage)
- By matching records of the groom with that of his father
- profession of the father (at father's marriage)
- profession of the grand-father (at father's marriage)
- 572 matched records (i.e. grooms whose father married also in Geneva)


## Trees for sequence data

- We shall focus on supervised trees and their use for sequence data.
- How is present state related to previous states? (Mobility analysis)
- How discriminating are specific sequencing patterns, for sex cohort, ...?
- How are typical sequencing patterns linked to covariates of interest?
- However, Will also shortly discuss typology of sequences (Hierarchical clustering)


## Mobility Tree <br> Examples to start with <br> Social mobility over 3 generations

## The social statuses

## 6 statuses derived from the professions

- unskilled: unskilled daily workmen, servants, labourer, ...
- craftsmen: skilled workmen
- clock makers: skilled persons working for the "Fabrique"
- white collars: teachers, clerks, secretaries, apprentices, ...
- petite et moyenne bourgeoisie: artists, coffee-house keepers, writers, students, merchants, dealers, ...
- élites: stockholders, landlords, householders, businessmen, bankers, army high-ranking officers, ...

[^0]
## Social statuses in 3 categories

For further simplification we consider also Statuses into 3 categories

| 3 class statuses | 6 class statuses |
| :--- | :--- |
| Low | unknown <br> unskilled <br> craftsmen |
| Clock | clock makers |
| High | white collars <br> PMB <br> elites |

## Mobility Tree

Examples to start with
Social mobility over 3 generations

## Father-Son Social Transition, Enrooted

Father to son social transition rates, Geneva 1830-1880, enrooted population (572 cases)

| Father | Son <br> unkwn | unskil | craft | clock | wcolar | PMB | élite | Total |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| unknown | $\cdot$ | . | $\mathbf{2 2 . 2}$ | 33.3 | $\mathbf{2 2 . 2}$ | $\mathbf{2 2 . 2}$ | . | 100 |
| unskilled | . | $\mathbf{2 7 . 3}$ | 9.1 | $\mathbf{3 6 . 4}$ | . | $\mathbf{2 7 . 3}$ | . | 100 |
| craftsman | . | 1.2 | $\mathbf{3 9 . 5}$ | 29.6 | 11.1 | 14.8 | 3.7 | 100 |
| clock maker | . | $\mathbf{7 . 2}$ | 4.8 | $\mathbf{6 3 . 9}$ | 8.4 | 13.3 | 2.4 | 100 |
| white collar | . | . | $\mathbf{2 7 . 8}$ | 22.2 | $\mathbf{1 6 . 7}$ | $\mathbf{2 7 . 8}$ | 5.6 | 100 |
| PMB | . | $\mathbf{7 . 4}$ | 10.3 | 20.6 | 2.9 | $\mathbf{4 7 . 1}$ | $\mathbf{1 1 . 8}$ | 100 |
| élite | 2.2 | 2.2 | 8.9 | 8.9 | 4.4 | $\mathbf{3 1 . 1}$ | $\mathbf{4 2 . 2}$ | 100 |
| deceased | . | $\mathbf{6 . 6}$ | 12.8 | $\mathbf{3 5 . 0}$ | $\mathbf{1 7 . 5}$ | 18.3 | 9.7 | 100 |
| Total | 0.2 | 5.8 | 15.4 | 34.3 | 12.2 | 22.0 | 10.1 | 100 |

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## Mobility Tree <br> Examples to start with <br> Three generations social transitions <br> Three generations social transitions

- Classical approach: Markov model up to order 3:
- Status at $t$ depends on statuses at $t-1, t-2$ and $t-3$ :

$$
p\left(s_{t} \mid s_{t-1}, s_{t-2}, s_{t-3}\right)
$$

holds for any status $s_{t}$.

- For 3 statuses, there are $3^{3}=27$ different conditions.
- Many free parameters (54) $\Rightarrow$ modeling probabilities in term of fewer parameters (Berchtold and Raftery, 2002)
- Can be done with Berchtold and Berchtold (2004)'s March software.
- Mobility tree: Flexible Markov model
- Each $s_{t}$ depends only on significant previous statuses.
- Classification tree for which the present status $s_{t}$ is the target and previous statuses $s_{t-1}, s_{t-2}, s_{t-3}$ are predictors.
- Easy to account for other covariates.


## Mobility Tre

Examples to start with
Three generations social transitions

## Covariate: Geographical Origin

| Code | Place |
| :--- | :--- |
| GEcity | Geneva city |
| GEland | Geneva surrounding land |
| neighbF | neighboring France |
| VD | Vaud |
| NE | Neuchatel |
| otherFrCH | other French speaking Switzerland |
| GermanCH | German speaking Switzerland |
| TI | Italian speaking Switzerland |
| F | France |
| D | Germany |
| I | Italy |
| other | other |

Three generations social transitions
Mobility tree for the 3 generations problem
Son's Status: Low (workers and craftsmen), Clock Maker, High


```
Mobility Tree
    Examples to start with
    Working statuses mobility
Mobility over working statuses
```

- (SHP Data, Waves 1 to 6 (1999-2004), aged between 20 and 64 in 2004.)
- How does working status (occupied active, unemployed, inactive) in 2004 depend on
- working status in previous year (1999 to 2003)
- other factors (attained education level, partner working status, partner education level, ...)
and what are main interaction effects?
- Mobility trees are alternative to Markovian transition models.
- Growing separate classification trees for women and men highlights gender differences.


## Mobility Tre

Examples to start with
Three generations social transitions
Tree quality

- Error rate: $42.4 \%$, i.e. $24 \%$ reduction of the classification error rate of the initial node
- Goodness of fit

| Tree | G2 | $d f$ | sig | BIC | AIC | pseudo $R^{2}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Indep | 482.3 | 324 | 0.000 | 2319.6 | 812.3 | 0 |
| Level 1 | 408.2 | 318 | 0.000 | 1493.9 | 750.2 | 0.14 |
| Level 2 | 356.0 | 310 | 0.037 | 1492.5 | 714.0 | 0.23 |
| Level 3 | 327.6 | 304 | 0.168 | 1502.2 | 697.6 | 0.28 |
| Fitted | 312.5 | 300 | 0.298 | 1512.5 | 690.5 | 0.30 |
| Saturated | 0 | 0 | 1 | 3104.7 | 978.0 | 1 |

## Mobility Tree <br> Examples to start with <br> Working statuses mobility

Mobility tree, Men


Working status B (full time, long part time, short part time, unemployed, inactive)

Mobility tree, Women


Working status B (full time, long part time, short part time, unemployed, inactive)
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```
Mobility Tree
    Incuction Trees
        Induction Trees: Introduction (2)
```

Singles out interactions of covariates in their effect on the response variable

Results:

- visual (a tree);
- no coefficients measuring the effect of covariates;
- classification rules.


## Mobility Tree

## Induction Trees

Induction Trees: Introduction (1)

- Trees induced from data.
- Recursive partitioning, segmentation, ...
- Most often used for classification: classification tree, when target is a categorical variable.
- Regression tree, when response variable is measurable at interval or ratio scale.
- Objective: Partition data according to explanatory factors (attributes, predictors, covariates) so that the distribution of the response variable (dependent variable to be predicted):
- is the purest possible in each class
(maximize class homogeneity $=$ minimize within class differences)
- differs as much as possible from one class to the other (maximize between class differences);

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```
Mobility Tree
    duction Trees
        htroduction
Illustration: Titanic
```



## Supervised learning

## Supervised learning

- Based on a learning sample $\left\{\left(\mathbf{x}_{\alpha}, y_{\alpha}\right)\right\}_{\alpha=1, \ldots, n}$,
- where $y_{\alpha}$ is the value (class) of the response (dependent, ...) variable for case $\alpha$,
- and $\mathbf{x}_{\alpha}=\left(x_{\alpha 1}, \ldots, x_{\alpha p}\right)$ is the profile of $\alpha$ in terms of the covariates.
- Build a predictive function (or classification function)

$$
y=f(\mathbf{x})
$$

with which we can predict the value or class $y$ when only the profile x is known.

- Example: predict whether a passenger of the Titanic survives from the sole knowledge of sex, age (child/adult) and navigation class.

```
Mobility Tree
    Tree Growing
```

```
ree Growing Principle
```


## Constructing the rules

An induction tree (like a logistic regression) determines the rule $f(x)$ in two steps
(1) Determine a partition of the possible profiles $x$ such that the distribution $p_{y}$ of the response $Y$ is as different as possible from one class to the other.

(2) The rule consists then in assigning to each case the most frequently observed value $y$ in the class defined by the values of $x$.

$$
\hat{y}=f(\mathbf{x})=\arg \max _{i} \hat{p}_{i}(\mathbf{x})
$$

## Mobility Tree

Induction Trees

## Tree Growing Principle

## Target Table

- Assuming all variables are categorical, we can represent the data with a contingency table that cross tabulates the response variable with a composite variable defined by the cross tabulation of all covariates.
- Example of a target contingency table T.
- Response variable is marital status, predictors are sex and sector of activity

|  | man |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| married | primary | secondary | tertiary | primary | woman <br> secondary | tertiary | total |
| no | 11 | 14 | 15 | 0 | 5 | 5 | 50 |
| yes | 8 | 8 | 9 | 10 | 7 | 8 | 50 |
| total | 19 | 22 | 24 | 10 | 12 | 13 | 100 |

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```
Mobility Tree
    Induction Trees
        Tree Growing Principle
        Induced Tree
```



- Partitions are determined by successive splits of nodes.
- Starting with the root node (formed by the set of all cases), we seek the covariate that permits the better split according to a given criterion (greatest entropy reduction, strongest association with the response.)
- Operation is repeated at each new obtained node until fulfilment of some stopping criterion (a minimal node size or a minimal gain in the criterion).


## The criteria

## Splitting criteria

## Criteria from

- Information Theory: Entropies (uncertainty) prediction made from the resulting distribution

$$
\begin{array}{ll}
\text { Shannon's entropy: } & h_{S}(p)=-\sum_{i=1}^{c} p_{i} \log _{2} p_{i} \\
\text { Quadratic entropy (Gini): } & h_{Q}(p)=\sum_{i=1}^{c} p_{i}\left(1-p_{i}\right)=1-\sum_{i=1}^{c} p_{i}^{2}
\end{array}
$$

$\Rightarrow$ maximizing entropy reduction
(maximizing within leaves homogeneity)

- Statistical associations: Pearson's Chi-square, measures of association.
$\Rightarrow$ maximizing association,
minimizing the $p$-value of the no-association test.
(maximizing diversity between leaves)
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Mobility Tree
Induction Trees
The criteria
$\quad$ Gain of information (2)
- Gain $=$ reduction of uncertainty
- Uncertainty: Shannon's entropy

$$
\begin{aligned}
H(\text { marital status }) & =-\sum_{i=1}^{c} p_{i} \log _{2} p_{i} \\
& =-\left(\frac{50}{100} \log _{2}\left(\frac{50}{100}\right)+\frac{50}{100} \log _{2}\left(\frac{50}{100}\right)\right)=1 \\
H(\text { marital status } \mid \text { man }) & =-\left(\frac{40}{65} \log _{2}\left(\frac{40}{65}\right)+\frac{25}{65} \log _{2}\left(\frac{25}{65}\right)\right)=.961 \\
H(\text { marital status } \mid \text { woman }) & =-\left(\frac{10}{35} \log _{2}\left(\frac{10}{35}\right)+\frac{25}{35} \log _{2}\left(\frac{25}{35}\right)\right)=.863 \\
H(\text { marital status } \mid \text { sex }) & =(65 / 100) 0.961+(35 / 100) 0.863=0.927 \\
\text { Gain(sex }) & =H(\text { marital status })-H(\text { marital status } \mid \text { sex }) \\
& =1-0.927=0.073
\end{aligned}
$$

## Mobility Tree

Induction Tree
The criteria
Gain of information (1)

- Splitting the root node by sex, we get two nodes.
- The distribution in each node is that of the corresponding column of Table below

| Marital status by sex |  |  |  |
| :---: | :---: | :---: | :---: |
| age man woman total |  |  |  |
| married | 40 | 10 | 50 |
| not married | 25 | 25 | 50 |
| total | 65 | 35 | 100 |

- What information brings "sex"?


## Mobility Tree <br> Induction Tree

The criteria

## Most popular tree growing methods

- CHAID, CHi-square based Automatic Interaction Detection (Kass, 1980; Biggs et al., 1991): $n$-ary trees, criterion based on Bonferroni adjusted $p$-values of independence tests.
- CHAID is an extension of an earlier regression tree method called AID (Morgan and Sonquist, 1963)
- CART, Classification and Regression Tree (Breiman et al., 1984): binary trees, criterion is maximizing decrease of Gini purity measure, pruning, surrogate splits in case of missing values.
- C4.5 (Quinlan, 1993): binary trees, criterion is Information Gain, the reduction in Shannon's entropy standardized by the entropy of the predictor.
- C4.5 was designed in a less statistical and more IA perspective.

Most popular tree growing methods (2)

- CART and C4.5 were designed for prediction purposes (prediction error is a primary concern).
- CHAID and AID primary aim is interaction detection. Their aim is primary description, rather than prediction.

```
Mobility Tree
    wition to the practice of decision trees with part
    Party
        party principle
```

- party selects each split in two steps (to avoid bias in favor of predictors with many different values):
- First, selects the predictor with strongest association with target,
- Then, selects the best binary split for selected predictor.


## obility Tree

itiation to the practice of decision trees with part

## Party

- There at least two packages in R for growing (binary) trees:
- rpart (Therneau and Atkinson, 1997): recursive partitioning CART, Relative risk trees,
- party (Hothorn et al., 2006): conditional partitioning

Based on a statistical conditional inference method (permutation tests)

- We discuss here only the second one
- much more powerful and flexible.
- better visual rendering (Plots distributions inside the nodes)


## Mobility Tree

nitiation to the practice of decision trees with party
Party

## Linear statistic and permutation test

- Both steps are based on the conditional distribution of linear statistics in a permutation test framework.
- Linear statistic is:

$$
\mathbf{T}_{j}=\operatorname{vec}\left(\sum_{i=1}^{n} w_{i} g_{j}\left(X_{j i}\right) h\left(\mathbf{Y}_{i},\left(\mathbf{Y}_{1}, \ldots, \mathbf{Y}_{n}\right)\right)^{T}\right) \in \mathbb{R}^{p_{j} q}
$$

where $g_{j}\left(X_{j i}\right)$ is a transformation of $X_{j i}$, and $h()$ an influence function.

- $\mathbf{T}_{j}$ is computed for each permutation of the $\mathbf{Y}$ values among cases, and results characterize its conditional independence distribution.
- the variable and split selection is then based on the $p$-value of the observed $\mathbf{t}$ under this conditional independence distribution.


## Creating or reading a data set in $R$

- You can either create a data.frame within R
\# creating data set in R
marr
data.frame (married="yes", sex="man", activity="primary", weight=11), data.frame (married="yes", sex="man", activity="secondary", weight=14),
data.frame (married="yes", sex="man",
activity="tertiary", weight=15) data.frame (married="yes",sex="woman", activity="primary", weight=0), data. frame (married="yes", sex=""oman", activity="secondary", weight=5), data.frame (married="yes", sex=""oman" ", activity="tertiary", weight=5),
data.frame (married="no", sex="man", activity="primary", weight=8),
 data. frame (married="no", sex="man", activity="tertiary", weight=9), data. frame (married=" "o", sex="woman", activity="primary", weight=10), data.frame (married="no", sex=""oman", activity="secondary", weight=7),
data.frame(married="no", sex="woman", activity="tertiary", weight=8) marr \# displays content of marr
- It is however more convenient to read a file, for instance a csv file
marr <- read.csv(file="C:/data/lund/exple_married_sex_sector.csv", header=TRUE)

```
Mobility Tree
    itiation to the practice of decision trees with party
    Party
Output in R console
```


## > marrtree

Conditional inference tree with 4 terminal nodes
Response: married
Inputs: sex, activit
Number of observations: 12

1) sex $==\{$ woman $\} ;$ criterion $=0.996$, statistic $=9.791$
2) activity $==\{$ secondary, tertiary\}; criterion $=0.874$, statistic $=5.471$
3)* weights $=25$
3) activity $==\{$ primary $\}$
4)* weights $=10$
4) sex $==\{\operatorname{man}\}$
5)* weights $=65$

## Mobility Tree

Initiation to the practice of decision trees with party
Party

## A R script for generating a tree

- You grow the tree with the ctree command
\#loading party
library(party)
marrtree <- ctree(married ~ ., data=marr [,1:3], weights=marr\$weight)
marrtree \# dispays info on tree
plot(marrtree) \# plots the tree
\# Plotting same tree using some controls.
plot (marrtree,drop_terminal=F,inner_panel=node_barplot)


## Mobility Tree <br> Initiation to the practice of decision trees with party <br> Party <br> Here is the first plotted tree

Response variable is: "married"


Mobility tree on the 3 generations mobility data

## State variables

\#\# Mobility tree example with data from marriage acts of 19th Century Geneva
library (foreign) \# library for importing data from various sources
sm_data <- read.spss(file="C:/data/lund/mobility/par_enf_tree_267.sav",to.data.frame=T)
sm_data\$NC1_ST3 <- factor(sm_data\&NC1_ST3) \# to remove deceased category
\# ordering and renaming state variables
seqs <- data.frame(GdFather=sm_data\$NG1ST_P3, Father_his_M = sm_data\$NP1_ST3,
\# Growing mob tree with ctree (party package)
library (party)
cl_tree <- ctree(seqs\$Son_M ~ seqs\$Father_son_M + seqs\$Father_his_M + seqs\$GdFather + sm_data\$C1LIEU11)
plot(cl_tree)
\# you may control the tree with ctree_control()
control <- ctree_control(testtype="Univariate",mincriterion=. 9 , minsplit=20, minbucket=10) cl_tree <- ctree (seqs\$Son_M ~ seqs $\$ F a t h e r_{-}$son_M + seqs $\$ F a t h e r_{\text {_his_M }}$ + seqs $\$ G d F a t h e r+$ sm_data\$C1LIEU11,controls=control)
plot(cl_tree,drop terminal=F)
slot(cl_tree,drop_terminal=F)

## Mobility Tree

Initiation to the practice of decision trees with party
Now building a mobility tree
Text output

Conditional inference tree with 8 terminal nodes
Response: seqs\$Son_M
Response: seqs\$Son_M
Inputs: seqs $\$$ sather_son_M, seqs $\$$ Father_his_M, seqs $\$ G d F a t h e r, ~ s m \_d a t a \$ C 1 L I E U 11 ~$
Number of observations: 267

1) seqs $\$$ FFather_his_M $=$ \{high $\}$; criterion $=1$, statistic $=48.744$
2) seqs $\$$ Father_son_M $_{\text {3) }}$ ( $=$ \{clock, deceased\}; criterion $=0.948$, statistic $=12.494$
3) $*$ weights $=38$
4) seqs $\$$ Father_son_M $=$ \{ $\{1$ ow, high $\}$
5) seqs $\$$ GdFather $==\{1$ low, clock $\}$; criterion $=0.918$, statistic $=6.709$
6) seqs\$GdFather $==\{\mathrm{high}$, deceased\}
$\begin{array}{rl}6) * \text { weights } & =29 \\ \text { segs } \$ \text { Father_his_M } & =\{ \end{array}$ \{low, clock $\}$
7) seqs $\$$ Father_his_M $=\{$ \{1ow, clock $\}$
seqs $\$$ Father_son_M $==\{$ clock, high, deceased\}; criterion $=0.998$, statistic $=20.864$
8) seqs $\$$ Father__his_M $==\{1$ out $\}$; criterion
9) seqs $\$$ FFather_his_M $==\{1$ ouk; criterion $=0.897$, statistic $=13.387$
10)* weights $=16$ (ciock, high $\}$; criterion $=0.992$, statistic $=17.472$
10) seqs $\$ G \mathrm{GFather}=\left\{\begin{array}{l}\text { low, deceased }\}\end{array}\right.$
11) seqs $\$ G d F a t h e r==\{1$ ow $\}$; criterion $=0.808$, statistic $=8.461$
12) w wights $=24$
13) seqs $\$$ GdFather $==\{$ deceased\} $\}$
14) seqs $\$$ Father_his_M $==\{c l o c k\}$
15) seqs $\$$ Father_his_M $==\{$ cloc $\}$
14)* weights $=76=\{1$ ww $\}$
16) seqs $\$$ Father_son_M $M=\{1$ ow $\}$
15)* weights $=43$

- Variables are

| variable | label |
| :--- | :--- |
| GdFather | 'Status Grd-father, 3 categories' |
| Father_his_M | 'Status Father (his marr.), 3 categories' |
| Father_son_M | 'Status Father (son"s marr.), 3 categories' |
| Son_M | 'Status Son (his marr.), 3 categories' |

## Mobility Tree <br> Initiation to the practice of decision trees with party <br> Now building a mobility tree

And here is the induced tree


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## Transition rates

- You may get transition rates with TraMineR

| > library (TraMineR) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| > seqtrate(seqs) |  |  |  |  |
| Computing transition rates between states clock deceased high low, please wait [-> clock] [-> deceased] [-> high] [-> low] |  |  |  |  |
| [clock ->] | 0.5062500 | 0.1562500 | 0.2625000 | 0.0750000 |
| [deceased ->] | 0.3333333 | 0.0000000 | 0.3607306 | 0.3059361 |
| [high ->] | 0.1641791 | 0.1492537 | 0.5621891 | 0.1243781 |
| [low ->] | 0.1357466 | 0.2352941 | 0.1764706 | 0.4524887 |

> library (TraMineR)
> seqtrate(seqs)
[-> clock] [-> deceased] [-> high] [-> low]
0.1492537 0.5621891 0.1243781
$>$

## Mobility Tree

Quality of the tree
Error rates and deviance

## Quality of the tree

- When the concern is classification, i.e. predicting the value of the response variable, we look typically at the error rate.
- Error rate should be computed on a test sample (different from learning sample).
- Cross-validation is often used.
- For non classification purposes (as is most often the case in social sciences)
- We can compute some deviance (Ritschard, 2006) that measures how far the obtained partition is from the finest one that can be defined with the predictors.
- Deviance reduction between nested models can be compared with Chi-square distributions (example).


## Mobility Tree <br> Quality of the tre

## Complexity

- Tree complexity:
- number of nodes
- number of levels
- message length (rules)
- We may reduce complexity
- a priori by reinforcing stopping rules
(e.g. maximal number of levels or minimal node size)
- a posteriori through pruning
(mainly used with non statistical splitting criteria, such as in CART)
- In statistics, complexity of model $=$ number of free parameters
- Can also be applied to trees.


## Quality of partitions

- Global improvement of criterion
- Gain of information between root node and set of all leaves (terminal nodes).
- Degree of association between target and final partition (GK $\tau$, Cramer's v, ...).
- $p$-value of independence test between target and partition (node numbers).
- With party, you may use the where(growntree) command to retrieve the node membership for each case.


## Mobility Tree <br> Discriminating with typical sequencing pattern

Frequencies of characteristic 2 -event sequences


## Discriminating with typical sequencing pattern

- Approach used by (Billari et al., 2006) on FFS data for Italy and Austria.
- Here we consider (SHP 2002 biographical data)
- Selection of pairs of events, e.g. marriage and first job.
- For each pair, order of sequence: $<,=,>$, missing
- Which are the most typical sequences?
- Most discriminating sequences between
- sex
- birth cohort (1940 and before, after 1940)


## Mobility Tree

Discriminating with typical sequencing pattern
Discriminating sex with 2-event sequences


[^1]
## Unsupervised trees

- Compute a distance or proximity matrix between sequences (OM or other metrics).
- Can be done with CHESA (Elzinga, 2007) or with TraMineR in R .
- Once you have the distance matrix you can make a hierarchical clustering and produce the dendrogram.


## Mobility Tree <br> Unsupervised trees: Dendrograms <br> Resulting dendrogram

## Dendrogram of agnes( $\mathrm{x}=$ dist.om1, diss $=$ TRUE, method $=$ " $w$



## obility Tree

Unsupervised trees: Dendrograms

## R script: hierarchical clustering

## library (TraMineR)

hvad <- read.csv(file="c:/data/lund/McVicar.csv", header=TRUE)
svar <- 15:86 \# sets the sequence to be considered
\# Computing OM distances
\# First we compute the substitution costs based on transition rates
submat <- seqsubm(mvad, svar,method= "TRATE")
and now the OM distances
ist.om1 <- seqdist(mvad, svar, format="STS", method="OM", indel=1, submat)
Hierarchical Clustering with Ward Metho
ibrary (cluster)
clusterward1 <- agnes(dist.om1, diss=TRUE, method="ward")
plot(clusterward1)
plot(clusterward1)
$\square$

Mobility Tree
Unsupervised trees: Dendrograms

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